

1. Let  $T : \mathbf{R}^a \rightarrow \mathbf{R}^b$  be the linear transformation defined as  $T(\mathbf{x}) = A\mathbf{x}$  where  $A = \begin{bmatrix} 2 & 2 & 1 \\ 9 & 7 & 3 \\ 4 & 0 & -1 \\ 11 & 5 & 1 \end{bmatrix}$

1A. What are  $a$  and  $b$ ?  $a = \square$   $b = \square$

1B. Find  $T\left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\right)$ .

1C. Let  $\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$ . Find any/all conditions that  $b_1, b_2, b_3,$  and  $b_4$  must satisfy in order for  $\mathbf{b}$  to be in the range of  $T$ .

1D. Verify that  $\mathbf{s} = \begin{bmatrix} 0 \\ 5 \\ 10 \\ 15 \end{bmatrix}$  satisfies the condition(s) in 1C.

1E. Find all  $\mathbf{x}$  such that  $T(\mathbf{x}) = \mathbf{s}$ .

**NOTE:** This is problem 1 continued!

**1F.** Suppose  $\mathbf{d} = \begin{bmatrix} -3 \\ 2 \\ d_3 \\ d_4 \end{bmatrix}$ . Use the conditions in (1C) to find all values of  $d_3$  and  $d_4$  for which  $\mathbf{d}$  is in the range of  $T$ . (Note you will be setting up a little linear system, and you should use our linear algebra techniques to solve it).

**1G.** Is  $T$  onto  $\mathbf{R}^b$ ? Explain why or why not.

**1H.** Is  $T$  one-to-one? Explain why or why not.

2. Let  $\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_6$  be the column vectors of  $Q = \begin{bmatrix} 6 & 7 & 10 & 1 & 8 & 17 \\ 4 & 6 & 12 & 2 & 5 & 18 \\ 3 & 3 & 3 & 1 & 4 & 11 \\ 2 & 1 & -2 & 0 & 3 & 4 \end{bmatrix}$  and let  $\mathbf{b} = \begin{bmatrix} 79 \\ 66 \\ 36 \\ 15 \end{bmatrix}$

2A. Use your calculator to find  $\text{rref}([Q|\mathbf{b}])$  and copy the result here:

2B. Find all solutions of  $Q\mathbf{x} = \mathbf{b}$  and express them in the parametric form  $\mathbf{x} = \mathbf{p} + \mathbf{v}_h$  where  $\mathbf{p}$  is a particular solution of  $Q\mathbf{x} = \mathbf{b}$  and  $\mathbf{v}_h$  gives all solutions of the corresponding homogeneous equation. *Circle and label* the two parts of your answer.

2C. Show that  $\mathbf{c}_2$  can be expressed as a linear combination of the other five column vectors; give an explicit LC.

2D. At least one of the column vectors is not a linear combination of the others. Find such a vector and explain why it can't be so expressed.

2E. Is the span of the set of column vectors of  $Q$  all of  $\mathbf{R}^4$ ? Explain your answer.

2F. Is the set  $\{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_6\}$  linearly independent? Explain why or why not.

**3.** A model for an economy uses 4 sectors  $A, B, C, D$ . Sector  $B$  consumes 10% of the output of  $A$ , twice that much of its own output, and  $2/5$  of  $D$ 's output. Sector  $C$  uses  $1/10$  of its own output and the remainder is consumed in equal portions by the other three sectors. Sector  $A$  consumes half of  $D$ 's output and *vice versa*;  $D$  also uses  $1/2$  of  $B$ 's output but  $A$  and  $D$  consume none of their own output. Sector  $C$  consumes as much of  $B$ 's output as  $B$  itself does.

**3A.** Remembering that the entries of each column sum to one, what is the exchange table for this economy?

**3B.** Suppose sector  $D$  has an equilibrium price of \$179 billion. What are the other three equilibrium prices  $P_A, P_B$  and  $P_C$ ? Label your answers.

4. Suppose  $T : \mathbf{R}^a \rightarrow \mathbf{R}^z$  is a transformation. Give the definitions of each of the following:

4a.  $T$  is a *linear* transformation.

4b.  $T$  is onto  $\mathbf{R}^z$ .

4c. Suppose  $T : \mathbf{R}^3 \rightarrow \mathbf{R}^4$  is defined by  $T \left( \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} x_2x_3 + x_1^2 \\ 0 \\ 3x_1 + 2x_2 + x_3 \\ 2x_2 + 7 \end{bmatrix}$ . Show by example that  $T$  is not a linear

transformation and that it actually fails both parts of the definition in (4a); use all-different numbers as entries in any vectors you use.

5. Suppose the solutions of a matrix equation  $A\mathbf{x} = \mathbf{b}$  are written in the form  $\mathbf{p} + \mathbf{v}_h$ , where  $\mathbf{p}$  is a particular solution of  $A\mathbf{x} = \mathbf{b}$  and  $\mathbf{v}_h$  gives all solutions of the corresponding homogeneous equation.

$$\text{Suppose } \mathbf{b} = \begin{bmatrix} 2 \\ -13 \\ 0 \\ 4 \end{bmatrix}, \mathbf{p} = \begin{bmatrix} 3 \\ 0 \\ 6 \\ -5 \\ 0 \end{bmatrix} \text{ and } \mathbf{v}_h = x_2 \begin{bmatrix} 8 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -7 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}, \text{ where } x_2 \text{ and } x_5 \text{ are free.}$$

5A. Although we don't know what the original  $A$  is, it is possible to say what the RREF of the augmented matrix  $[A|\mathbf{b}]$  is. Give it:

5B. Label the columns of (the unseen)  $A$  as  $\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k$ . Is the set  $S = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k\}$  *linearly independent*? Explain in terms of the definition of linear independence.