

**MATH 205A,B LINEAR ALGEBRA - PROF. P. WONG**

EXAM I - OCTOBER 7, 2015

**NAME:** \_\_\_\_\_ **Section:**(Circle one)    A(8 : 00)    B(9 : 30)

Instruction: Read each question carefully. Explain **ALL** your work and give reasons to support your answers.

*Advice:* DON'T spend too much time on a single problem.

<b>Problems</b>	<b>Maximum Score</b>	<b>Your Score</b>
1.	20	
2.	20	
3.	20	
4.	20	
5.	20	
<b>Total</b>	100	

1. Consider the following system of linear equations

$$(1) \quad \begin{aligned} 4x_1 - 2x_2 + 7x_3 &= -5 \\ 8x_1 - 3x_2 + 10x_3 &= -3. \end{aligned}$$

(a) Find the solutions to the system (1), if it is consistent.

Consider the associated augmented matrix

$$\begin{bmatrix} 4 & -2 & 7 & -5 \\ 8 & -3 & 10 & -3 \end{bmatrix}.$$

Note that

$$\begin{bmatrix} 4 & -2 & 7 & -5 \\ 8 & -3 & 10 & -3 \end{bmatrix} \sim \begin{bmatrix} 4 & -2 & 7 & -5 \\ 0 & 1 & -4 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & -1/2 & 7/4 & -5/4 \\ 0 & 1 & -4 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1/4 & 9/4 \\ 0 & 1 & -4 & 7 \end{bmatrix}.$$

Thus we conclude that  $x_1 - \frac{1}{4}x_3 = \frac{9}{4}$  and  $x_2 - 4x_3 = 7$ . In other words,

$$\begin{aligned} x_1 &= \frac{9}{4} + \frac{1}{4}x_3 \\ x_2 &= 7 + 4x_3 \\ x_3 &= \text{free variable} \end{aligned}$$

(b) Find the solutions to the homogeneous system

$$\begin{aligned} 4x_1 - 2x_2 + 7x_3 &= 0 \\ 8x_1 - 3x_2 + 10x_3 &= 0. \end{aligned}$$

Using the calculations in part (a), the augmented matrix of the homogeneous system is row equivalent to

$$\begin{bmatrix} 1 & 0 & -1/4 & 0 \\ 0 & 1 & -4 & 0 \end{bmatrix}.$$

In other words,

$$\begin{aligned} x_1 &= \frac{1}{4}x_3 \\ x_2 &= 4x_3 \\ x_3 &= \text{free variable} \end{aligned}$$

2. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear transformation given by

$$T(x_1, x_2) = (3x_1 + 2x_2, -x_1 + 3x_2, x_1 + x_2).$$

(a) Find all  $\vec{x}$  such that  $T(\vec{x}) = \vec{0}$ .

**If  $T(x_1, x_2) = \vec{0}$  then  $-x_1 + 3x_2 = 0$  or  $x_1 = 3x_2$ . Moreover,  $x_1 + x_2 = 0$  implies that  $x_1 = -x_2$ . It follows that  $3x_2 = -x_2$  so  $x_2 = 0$  and hence  $x_1 = 0$ . Hence,  $T(x_1, x_2) = \vec{0}$  implies that  $x_1 = 0 = x_2$ .**

(b) Determine whether  $T$  is one-to-one. Justify your answer.

**From (a),  $T(\vec{x}) = \vec{0}$  has only the trivial solution so  $T$  is one-to-one.**

(c) Determine whether  $T$  is onto. Justify your answer.

**First, the matrix of  $T$  is given by**

$$A = \begin{bmatrix} 3 & 2 \\ -1 & 3 \\ 1 & 1 \end{bmatrix}$$

**so that  $T(\vec{x}) = A\vec{x}$ . Then  $T$  is onto if and only if the columns of  $A$  span the codomain which is  $\mathbb{R}^3$ . The matrix  $A$  has only two columns so they cannot span  $\mathbb{R}^3$ . Thus, we conclude that  $T$  is NOT onto.**

3. Let

$$B = \begin{bmatrix} 1 & -2 & -1 \\ -2 & 5 & 3 \end{bmatrix}.$$

(a) Are the columns of  $B$  linearly independent? Justify your answer.

**Note that the third column is the sum of the first and second column. It follows that the columns are NOT linearly independent.**

(b) Do the columns of  $B$  span  $\mathbb{R}^2$ ? Justify your answer.

**Observe that**

$$B = \begin{bmatrix} 1 & -2 & -1 \\ -2 & 5 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 \\ 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}.$$

**Thus,  $B\vec{x} = \vec{b}$  always has a solution for any  $\vec{b}$  or every row has a pivot. It follows that the columns of  $B$  span  $\mathbb{R}^2$ .**

(c) Write a formula for the linear transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  so that  $T(\vec{x}) = B\vec{x}$  for any vector  $\vec{x}$  in  $\mathbb{R}^3$ .

**If  $T(\vec{x}) = B\vec{x}$  then**

$$T(x_1, x_2, x_3) = (x_1 - 2x_2 - x_3, -2x_1 + 5x_2 + 3x_3).$$

4. Use elementary row operations to find the inverse  $A^{-1}$  of the following invertible matrix

$$A = \begin{bmatrix} 1 & 3 & 8 \\ 2 & 4 & 11 \\ 1 & 2 & 5 \end{bmatrix}.$$

(Show all your steps.)

**Note that**

$$\begin{aligned} & \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 2 & 4 & 11 & 0 & 1 & 0 \\ 1 & 2 & 5 & 0 & 0 & 1 \end{array} \right] \sim \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & -2 \\ 1 & 2 & 5 & 0 & 0 & 1 \end{array} \right] \sim \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 1 & 2 & 5 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \\ & \sim \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 0 & -1 & -3 & -1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \sim \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 0 & 1 & 3 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \sim \left[ \begin{array}{ccc|ccc} 1 & 3 & 8 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & -3 & 5 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \\ & \sim \left[ \begin{array}{ccc|ccc} 1 & 0 & 8 & -2 & 9 & -15 \\ 0 & 1 & 0 & 1 & -3 & 5 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \sim \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -2 & 1 & 1 \\ 0 & 1 & 0 & 1 & -3 & 5 \\ 0 & 0 & 1 & 0 & 1 & -2 \end{array} \right] \end{aligned}$$

It follows that the inverse of  $A$  is given by

$$A^{-1} = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -3 & 5 \\ 0 & 1 & -2 \end{bmatrix}.$$

5. (a) Let  $S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a transformation given by

$$S(x, y) = (1 - xy, x + y).$$

Determine whether  $S$  is a **linear** transformation. Explain.

**For  $S$  to be linear,  $S(k\vec{u}) = kS(\vec{u})$  for any vector  $\vec{u}$  and any constant  $k$ . Take  $\vec{u} = (2, 2)$  and  $k = 2$ . Then**

$$S(2(2, 2)) = S(4, 4) = (1 - 16, 4 + 4) = (-15, 8).$$

**On the other hand,**

$$2S((2, 2)) = 2(1 - 4, 2 + 2) = (-6, 8) \neq (-15, 8) = S(2(2, 2)).$$

**Hence,  $S$  is NOT linear.**

(b) Let  $A = \begin{bmatrix} 1 & -3 & 0 \\ -4 & 1 & 1 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ -1 & 1 \end{bmatrix}$ . Find (i)  $AB$ ; (ii)  $BA^T$ ; and (iii)  $A - B^T$ .

**First,**

$$A^T = \begin{bmatrix} 1 & -4 \\ -3 & 1 \\ 0 & 1 \end{bmatrix} \quad \text{and} \quad B^T = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \end{bmatrix}.$$

**It follows that**

$$AB = \begin{bmatrix} 1 & -3 & 0 \\ -4 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ 0 & -3 \end{bmatrix}.$$

**Similarly,**

$$A^T B^T = \begin{bmatrix} 1 & -4 \\ -3 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -4 & 1 & -5 \\ 1 & -3 & 4 \\ 1 & 0 & 1 \end{bmatrix}$$

**and**

$$A - B^T = \begin{bmatrix} 1 & -3 & 0 \\ -4 & 1 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -4 & 1 \\ -5 & 1 & 0 \end{bmatrix}.$$