

**MATH 205A,B LINEAR ALGEBRA - PROF. P. WONG**

EXAM II - MARCH 18, 2013

**NAME:** \_\_\_\_\_ **Section:**(Circle one)    A(1 : 10)    B(2 : 40)

Instruction: Read each question carefully. Explain **ALL** your work and give reasons to support your answers.

*Advice:* DON'T spend too much time on a single problem.

<b>Problems</b>	<b>Maximum Score</b>	<b>Your Score</b>
1.	20	
2.	20	
3.	20	
4.	20	
5.	20	
<b>Total</b>	100	

1. Let

$$A = \begin{bmatrix} 2 & 3 \\ 2 & 1 \end{bmatrix}.$$

(a)(7 pts) Find the eigenvalues of  $A$ .

**The eigenvalues of  $A$  are the solutions to  $\det(A - \lambda I) = 0$ . Note that**

$$\det(A - \lambda I) = \det \begin{bmatrix} 2 - \lambda & 3 \\ 2 & 1 - \lambda \end{bmatrix} = (2 - \lambda)(1 - \lambda) - 6 = \lambda^2 - 3\lambda - 4 = (\lambda - 4)(\lambda + 1).$$

**It follows that the eigenvalues of  $A$  are 4 and  $-1$ .**

(b)(7 pts) For each of the eigenvalue found in (a), determine the corresponding eigenspaces by giving a basis for each such subspace.

**For  $\lambda = 4$ ,  $A - 4I = \begin{bmatrix} -2 & 3 \\ 2 & -3 \end{bmatrix} \sim \begin{bmatrix} -2 & 3 \\ 0 & 0 \end{bmatrix}$ . It follows that the corresponding eigenspace is  $\left\{ x_2 \begin{bmatrix} 3/2 \\ 1 \end{bmatrix} : x_2 \text{ in } \mathbb{R} \right\}$  with  $\left\{ \begin{bmatrix} 3/2 \\ 1 \end{bmatrix} \right\}$  as a basis.**

**Similarly for  $\lambda = -1$  we have  $A + I = \begin{bmatrix} 3 & 3 \\ 2 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ . It follows that the corresponding eigenspace is  $\left\{ x_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} : x_2 \text{ in } \mathbb{R} \right\}$  with  $\left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$  as a basis.**

(c)(6 pts) Is  $A$  diagonalizable? If so, find an invertible matrix  $P$  such that  $P^{-1}AP$  is diagonal.

**The matrix  $A$  is diagonalizable since  $A$  has distinct eigenvalues and hence the two vectors  $\begin{bmatrix} 3/2 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  are linearly independent eigenvectors. Thus the matrix given by**

$$P = \begin{bmatrix} 3/2 & -1 \\ 1 & 1 \end{bmatrix}$$

**diagonalizes  $A$ .**

2. Let

$$A = \begin{bmatrix} 1 & 4 & 3 & -1 \\ 0 & 1 & 2 & -1 \\ 2 & 5 & 0 & 0 \end{bmatrix}.$$

(a)(8 pts) Find a basis for the column space  $\text{Col}A$  of  $A$ .

Using row reduction, we have

$$A = \begin{bmatrix} 1 & 4 & 3 & -1 \\ 0 & 1 & 2 & -1 \\ 2 & 5 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 3 & -1 \\ 0 & 1 & 2 & -1 \\ 0 & -3 & -6 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 3 & -1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -5 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -5 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

The first, second, and fourth columns contain pivots so a basis for  $\text{Col}A$  is  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 1 \\ 5 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix} \right\}$ .

(b)(8 pts) Find a basis for the null space  $\text{Nul}A$  of  $A$ .

From the calculation in (a), the null space of  $A$  is

$$\text{Nul}A = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 5x_3 \\ -2x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} 5 \\ -2 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

Thus a basis for  $\text{Nul}A$  is  $\left\{ \begin{bmatrix} 5 \\ -2 \\ 1 \\ 0 \end{bmatrix} \right\}$ .

(c)(4 pts) What is the rank of  $A$ ? Justify your answer.

Since  $A$  is a  $3 \times 4$  matrix, the Rank Theorem states that  $\text{rank}A + \dim \text{Nul}A = 4$ . Since  $\dim \text{Nul}A = 1$  from (b), it follows that  $\text{rank}A = 4 - 1 = 3$ .

3. (a)(5 pts) Let  $A$  be a  $4 \times 3$  matrix. If  $\dim \text{Nul}A = 3$ , what is the rank of  $A$ ? Justify your answer.

**The Rank Theorem asserts that  $\text{rank}A + \dim \text{Nul}A = n = 3$ . It follows that  $\text{rank}A = 0$ . For instance,  $A$  could be the zero matrix.**

(b)(5 pts) Suppose  $B$  is a  $5 \times 5$  matrix with eigenvalues  $2, -1, 4$  such that the eigenspace corresponding to  $2$  has dimension  $2$ ; the eigenspace corresponding to  $-1$  has dimension  $1$ ; and the eigenspace corresponding to  $4$  has dimension  $1$ . Determine whether  $B$  is diagonalizable. Justify your answer.

**The matrix  $B$  is NOT diagonalizable because there are four but not five linearly independent eigenvectors.**

(c)(5 pts) Let  $B$  be the matrix as in (b). Find  $\det(B + I)$ , the determinant of the matrix  $(B + I)$ . Justify your answer.

**Since  $-1$  is an eigenvalue of  $B$ ,  $-1$  is a solution to  $\det(B - \lambda I) = 0$  so  $\det(B + I) = 0$ .**

(d)(5 pts) Let  $B$  be the matrix as in (b). What is the dimension of  $\text{Col}(B - 2I)$ ? Justify your answer.

**Since  $2$  is an eigenvalue of  $B$ , the null space  $\text{Nul}(B - 2I)$  is the same as the eigenspace of  $B$  corresponding to the eigenvalue  $\lambda = 2$ . Thus,  $\dim \text{Nul}(B - 2I) = 2$ . Again, the Rank Theorem asserts that**

$$\dim \text{Col}(B - 2I) + \dim \text{Nul}(B - 2I) = 5.$$

**It follows that  $\dim \text{Col}(B - 2I) = 5 - 2 = 3$ .**

4. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation given by

$$T(x_1, x_2) = (x_1 + x_2, -4x_1 - 3x_2).$$

Consider the basis  $\mathcal{B} = \left\{ \begin{bmatrix} 3 \\ -5 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \end{bmatrix} \right\}$ .

(a)(8 pts) Find the  $\mathcal{B}$ -matrix of the transformation  $T$ .

**Note that**  $T\left(\begin{bmatrix} 3 \\ -5 \end{bmatrix}\right) = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$  **and**  $T\left(\begin{bmatrix} -2 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ . **The coordinate matrix**  $P_{\mathcal{B}} = \begin{bmatrix} 3 & -2 \\ -5 & 3 \end{bmatrix}$

**so the inverse is**  $P_{\mathcal{B}}^{-1} = \frac{1}{(-1)} \begin{bmatrix} 3 & 2 \\ 5 & 3 \end{bmatrix}$ . **Now,**

$$\left[ T\left(\begin{bmatrix} 3 \\ -5 \end{bmatrix}\right) \right]_{\mathcal{B}} = \frac{1}{(-1)} \begin{bmatrix} 3 & 2 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

**and**

$$\left[ T\left(\begin{bmatrix} -2 \\ 3 \end{bmatrix}\right) \right]_{\mathcal{B}} = \frac{1}{(-1)} \begin{bmatrix} 3 & 2 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -2 \end{bmatrix}.$$

**Therefore the  $\mathcal{B}$ -matrix of the transformation  $T$  is given by**  $M = \begin{bmatrix} 0 & -1 \\ 1 & -2 \end{bmatrix}$ .

(b)(6 pts) Suppose  $\vec{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ . Find  $[T(\vec{x})]_{\mathcal{B}}$ , the  $\mathcal{B}$ -coordinates of  $T(\vec{x})$ .

**First,**  $[\vec{x}]_{\mathcal{B}} = P_{\mathcal{B}}^{-1}\vec{x} = \begin{bmatrix} -8 \\ -13 \end{bmatrix}$ . **It follows that**  $[T(\vec{x})]_{\mathcal{B}} = M[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 0 & -1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} -8 \\ -13 \end{bmatrix} = \begin{bmatrix} 13 \\ 18 \end{bmatrix}$ .

**[Alternatively,**  $T(\vec{x}) = \begin{bmatrix} 3 \\ -11 \end{bmatrix}$  **so that**  $[T(\vec{x})]_{\mathcal{B}} = P_{\mathcal{B}}^{-1} \begin{bmatrix} 3 \\ -11 \end{bmatrix}$ .]

(c)(6 pts) If  $\mathcal{C} = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$  is another basis, find  $[T(\vec{x})]_{\mathcal{C}}$ .

**Using  $\mathcal{C}$ , the corresponding coordinate matrix is**  $P_{\mathcal{C}} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$  **so that its inverse is**

$P_{\mathcal{C}}^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$ . **It follows that**

$$[[T(\vec{x})]_{\mathcal{C}}] = P_{\mathcal{C}}^{-1} \begin{bmatrix} 3 \\ -11 \end{bmatrix} = \begin{bmatrix} 14 \\ -25 \end{bmatrix}.$$

5. (a)(7 pts) Find a basis for the subspace  $H$  of  $\mathbb{R}^3$  spanned by the vectors  $\begin{bmatrix} 2 \\ -5 \end{bmatrix}$ ,  $\begin{bmatrix} -4 \\ 10 \end{bmatrix}$ ,  $\begin{bmatrix} -3 \\ 6 \end{bmatrix}$ .

Note that the first two vectors are scalar multiples of each other whereas the first and the third vectors are linearly independent. In other words, the subspace  $H$  can be spanned by the first and the third vectors so a basis for  $H$  is  $\left\{ \begin{bmatrix} 2 \\ -5 \end{bmatrix}, \begin{bmatrix} -3 \\ 6 \end{bmatrix} \right\}$ .

(b)(7 pts) Let  $T : \mathbb{P}_2 \rightarrow \mathbb{R}^2$  be the linear transformation given by  $T(\mathbf{p}) = \begin{bmatrix} \mathbf{p}(0) \\ \mathbf{p}(0) \end{bmatrix}$ . Find polynomials  $\mathbf{p}_1, \mathbf{p}_2$  in  $\mathbb{P}_2$  that span the kernel of  $T$ .

The kernel  $\text{Ker}T$  of  $T$  is the set  $\{\mathbf{p} : T(\mathbf{p}) = \vec{0}\}$ . Since every  $\mathbf{p}$  in  $\mathbb{P}_2$  is of the form  $\mathbf{p}(t) = a + bt + ct^2$ ,  $\mathbf{p}$  lies in  $\text{Ker}T$  means that  $\mathbf{p}(0) = a$  must be 0. It follows that  $\text{Ker}T$  consists of all polynomials from  $\mathbb{P}_2$  with zero constant term, or polynomials of the form  $bt + ct^2$ . Thus,  $\mathbf{p}_1 = t, \mathbf{p}_2 = t^2$  span  $\text{Ker}T$ .

(c)(6 pts) Let  $\lambda$  be an eigenvalue of an  $n \times n$  invertible matrix  $A$  and  $\lambda \neq 0$ . Show that  $\frac{1}{\lambda}$  is an eigenvalue of  $A^{-1}$ . [Hint: Let  $\vec{v}$  be an eigenvector of  $A$  corresponding to  $\lambda$ .]

Let  $\vec{v}$  be an eigenvector of  $A$  corresponding to  $\lambda$ . Since  $\lambda \neq 0$ , we have  $A\vec{v} = \lambda\vec{v}$  or  $\frac{1}{\lambda}A\vec{v} = \vec{v}$ . Now multiply this equality by  $A^{-1}$  from the left on both sides, we obtain  $\frac{1}{\lambda}\vec{v} = A^{-1}\vec{v}$ . In other words, the same vector  $\vec{v}$  is an eigenvector of  $A^{-1}$  corresponding to the eigenvalue  $\frac{1}{\lambda}$ .