

Math 205 - Exam 2 - March 8, 2006

Instructions: Show enough work to justify your final answers. When referring to a theorem, give as much information about the theorem as you can.

1. (20 pts.) Consider the matrix $A = \begin{bmatrix} 1 & 2 & -2 & 7 & 6 \\ 2 & 2 & -4 & 10 & 8 \\ 0 & 1 & 0 & 2 & 2 \\ -2 & 2 & 4 & -2 & 6 \end{bmatrix}$, which is row-equivalent to $B = \begin{bmatrix} \textcircled{1} & 2 & -2 & 7 & 6 \\ 0 & \textcircled{1} & 0 & 2 & 2 \\ 0 & 0 & 0 & 0 & \textcircled{6} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$.

- What is the rank of A ?
- What is the dimension of the nullspace of A ?
- Find a basis for $\text{Col } A$.
- Find a basis for $\text{Row } A$.
- Find a basis for $\text{Nul } A$.

a) B has 3 pivots, so A has 3 pivots, so $\text{rank}(A) = \boxed{3}$.

b) A has rank 3, and $\dim(\text{Nul } A) = n - \text{rank}(A)$
 $= 5 - 3 = \boxed{2}$

c) Pivots in B are in columns 1, 2, 5. So basis for $\text{Col } A$ is

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ -2 \\ 6 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \\ 2 \\ 6 \end{bmatrix}, \begin{bmatrix} 6 \\ 2 \\ 0 \\ 0 \\ 6 \end{bmatrix} \right\}$$

d) Take rows in B that have pivots.

\rightarrow Basis for $\text{Row } A = \left\{ (1, 2, -2, 7, 6), (0, 1, 0, 2, 2), (0, 0, 0, 0, 6) \right\}$.

e) Solve $A\vec{x} = \vec{0}$. Use augmented matrix

$$[A \vec{0}] \sim [B \vec{0}] \sim \begin{bmatrix} 1 & 0 & -2 & 7 & 6 & 0 \\ 0 & 1 & 0 & 2 & 2 & 0 \\ 0 & 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 - 2x_3 + 7x_4 + 6x_5 = 0 \\ x_2 + 2x_4 + 2x_5 = 0 \\ x_5 = 0 \\ x_3, x_4 \text{ free.} \end{array}$$

So $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_3 - 7x_4 \\ -2x_4 - 2x_5 \\ x_3 \\ x_4 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -7 \\ -2 \\ 0 \\ 1 \\ 0 \end{bmatrix}$. Thus, a basis for $\text{Nul } A$ is $\left\{ \begin{bmatrix} 2 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -7 \\ -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$.

2. (15 pts.) Consider the matrix $M = \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 2 \\ -1 & -1 & 4 \end{bmatrix}$ and vector $\mathbf{v} = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}$.

- (a) Calculate $\det M$.
 (b) Is \mathbf{v} in $\text{Col } M$?
 (c) Is \mathbf{v} in $\text{Nul } M$?
 (d) Is \mathbf{v} an eigenvector of M ?
 (e) Show that $\lambda = 2$ is an eigenvalue of M and calculate its associated eigenspace.

a) $M \sim \begin{bmatrix} 1 & -1 & 2 \\ 0 & 0 & 4 \\ 0 & -2 & 6 \end{bmatrix}$ (adding row 1 to rows 2 and 3) So $|M| = \begin{vmatrix} 1 & -1 & 2 \\ 0 & 0 & 4 \\ 0 & -2 & 6 \end{vmatrix}$
 $\sim \begin{bmatrix} 1 & -1 & 2 \\ 0 & -2 & 6 \\ 0 & 0 & 4 \end{bmatrix}$ (switching rows 2 and 3).
 $= - \begin{vmatrix} 1 & -1 & 2 \\ 0 & -2 & 6 \\ 0 & 0 & 4 \end{vmatrix}$
 $= - (1)(-2)(4)$
 $= 8.$

b) $M\vec{x} = \vec{v}$ has a sol'n? Aug. matrix $[M \vec{v}] = \begin{bmatrix} 1 & -1 & 2 & 3 \\ -1 & 1 & 2 & 1 \\ -1 & -1 & 4 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & -2 & 6 & 5 \end{bmatrix}$
 No pivot in last column of $[M \vec{v}]$, so there is a solution. (Or note $|M| \neq 0$, so M is invertible, so $\vec{x} = M^{-1}\vec{v}$.) So $\vec{v} \in \text{Col } M$.

c) $M\vec{v} = \begin{bmatrix} 6 \\ 2 \\ 4 \end{bmatrix} \neq \vec{0}$. So \vec{v} is not in $\text{Nul } M$.

d) $M\vec{v} = \begin{bmatrix} 6 \\ 2 \\ 4 \end{bmatrix} = 2\vec{v}$. So \vec{v} is an eigenvector with eigenvalue $\lambda = 2$.

e) $(M - 2I)\vec{x} = \vec{0}$. Aug matrix is $\begin{bmatrix} -1 & -1 & 2 & 0 \\ -1 & -1 & 2 & 0 \\ -1 & -1 & 2 & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$
 $\sim \begin{bmatrix} 1 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

So $x_1 = -x_2 + 2x_3$.
 x_2, x_3 free.

$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -x_2 + 2x_3 \\ x_2 \\ x_3 \end{pmatrix} = x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$

$\lambda = 2$ has associated eigenspace
 $\text{Span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \right\}$.

3. (10 pts.) Let $B = \{1 - t - t^2, -1 + t - t^2, 2 + 2t + 4t^2\}$ be a set of polynomials in \mathbb{P}_2 .

(a) Show that B is a basis for \mathbb{P}_2 .

(b) For $p(t) = 3 + t + t^2$, find $[p]_B$.

(c) Is B a basis for \mathbb{P}_3 ? Explain.

a) View polys as vectors in \mathbb{R}^3 . $\rightarrow \left\{ \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 4 \end{bmatrix} \right\}$.

Independent? $\begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 2 \\ -1 & -1 & 4 \end{bmatrix}$ is M from problem 2, so $|M| = 8 \neq 0$,

so M is invertible, so its columns are independent.

Thus, since $\dim(\mathbb{P}_2) = 3$ and B is a linearly independent set of 3 polynomials, B is a basis for \mathbb{P}_2 .

b) Solve $\begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 2 \\ -1 & -1 & 4 \end{bmatrix} \vec{c} = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$. Use an augmented matrix

$$\begin{bmatrix} 1 & -1 & 2 & 3 \\ -1 & 1 & 2 & 1 \\ -1 & -1 & 4 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & -2 & 6 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 2 & 3 \\ 0 & -2 & 6 & 4 \\ 0 & 0 & 11 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & 1 \\ 0 & -2 & 0 & -2 \\ 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\boxed{\text{So } [p]_B = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}}$$

c) $\dim(\mathbb{P}_3) = 4$, so B would need 4 polynomials in order to be a basis.

Sadly, it has only 3.

Thus, B is not a basis for \mathbb{P}_3 .

4. (10 pts.) Prove the statement: If A is a $m \times n$ matrix, then $\text{Nul } A$ is a subspace of \mathbb{R}^n .

$\text{Nul } A = \{ \vec{x} : A\vec{x} = \vec{0} \}$. Certainly $\text{Nul } A$ is a subset of \mathbb{R}^n because if A is $m \times n$ and $A\vec{x} = \vec{0}$, then \vec{x} is $n \times 1$. Now we show it's a subspace. Need to verify the 3 properties:

(1) $\vec{0} \in \text{Nul } A$?

$A\vec{0} = \vec{0}$, so $\vec{0}$ is in $\text{Nul } A$.

(2) If $\vec{u}, \vec{v} \in \text{Nul } A$, is $(\vec{u} + \vec{v}) \in \text{Nul } A$?

If $\vec{u}, \vec{v} \in \text{Nul } A$, then $A\vec{u} = \vec{0}$ and $A\vec{v} = \vec{0}$. So $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v} = \vec{0} + \vec{0} = \vec{0}$.
So $\vec{u} + \vec{v} \in \text{Nul } A$.

(3) If $\vec{u} \in \text{Nul } A$, is $c\vec{u} \in \text{Nul } A$ for any constant c ?

$\vec{u} \in \text{Nul } A \Rightarrow A\vec{u} = \vec{0}$. So $A(c\vec{u}) = c(A\vec{u}) = c\vec{0} = \vec{0}$.
So $c\vec{u} \in \text{Nul } A$.

Thus, $\text{Nul } A$ is a subspace of \mathbb{R}^n !

5. (15 pts.) Let $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$, $B = \begin{bmatrix} a & b & c \\ d+2a & e+2b & f+2c \\ g+3a & h+3b & i+3c \end{bmatrix}$, and $C = \begin{bmatrix} g & h & i \\ 2d & 2e & 2f \\ a & b & c \end{bmatrix}$. Suppose $\det A = 5$.

(a) Find $\det(B)$.

(b) Find $\det(AC)$.

(c) Is AB invertible? Explain.

(d) Are the columns of A linearly independent? Explain.

a) $|B| = |A| = 5$ (adding mults of one row to another leaves determinant unchanged)

b) $|AC| = |A||C| = (5)|C|$. And $|C| = -2|A| = -10$ due to row scaling by 2 and a row flip.

Thus, $|AC| = 5(-10) = -50$.

c) $|AB| = |A||B| = 5 \cdot 5 = 25 \neq 0$, so since the determinant is non-zero, AB is invertible.

d) $|A| \neq 0$, so A is invertible. By Inverse Matrix Theorem, the columns of A are independent.

6. (10 pts.) Suppose A is a $n \times n$ matrix with the property that the equation $Ax = b$ has at least one solution for each b in \mathbb{R}^n . Prove that each equation $Ax = b$ has *exactly* one solution.

If $A\vec{x} = \vec{b}$ always has a solution, then by TFAE Thm (in 1.4), A has a pivot in each row. So A has n pivots. So A has a pivot in each column. So $A\vec{x} = \vec{b}$ has no free variables. So $A\vec{x} = \vec{b}$ has at most one solution. And since it always has at least one solution, the conclusion is that $A\vec{x} = \vec{b}$ has exactly one solution.

